

# Using Semantics & Statistics to Turn Data into Knowledge

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## Abstract

Many information extraction and knowledge base construction systems are addressing the challenge of deriving knowledge from text. A key problem in constructing these knowledge bases from sources like the web is overcoming the erroneous and incomplete information found in millions of candidate extractions. To solve this problem, we turn to semantics – using ontological constraints between candidate facts to eliminate errors. In this article, we represent the desired knowledge base as a knowledge graph and introduce the problem of *knowledge graph identification*, collectively resolving the entities, labels, and relations present in the knowledge graph. Knowledge graph identification requires reasoning jointly over millions of extractions simultaneously, posing a scalability challenge to many approaches. We use probabilistic soft logic (PSL), a recently-introduced statistical relational learning framework, to implement an efficient solution to knowledge graph identification and present state-of-the-art results for knowledge graph construction while performing an order of magnitude faster than competing methods.

A growing body of research focuses on extracting knowledge from text such as news reports, encyclopedic articles and scholarly research in specialized domains. Much of this data is freely available on the World Wide Web and harnessing the knowledge contained in millions of web documents remains a problem of particular interest. The scale and diversity of this content poses a formidable challenge for systems designed to extract this knowledge. Many well-known broad domain and open information extraction systems seek to build knowledge bases from text, including the Never-Ending Language Learning (NELL) project (Carlson et al., 2010), OpenIE (Etzioni et al., 2008), DeepDive (Niu et al., 2012), and efforts at Google (Pasca et al., 2006). Ultimately, these information extraction systems produce a collection of candidate facts, that include a set of entities, attributes of these entities, and the relations between these entities.

Information extraction systems use a sophisticated collection of strategies to generate candidate facts from web documents, spanning the syntactic, lexical and structural features of text (Weikum and Theobald, 2010; Wimalasuriya and Dou, 2010). While these systems are capable of extracting many candidate facts from the web, their output is of-

ten hampered by noise. Documents contain inaccurate, outdated, incomplete, or hypothetical information, and informal and creative language used in web documents is often difficult to interpret. As a result, the candidates produced by information extraction systems often miss key facts and include spurious outputs, compromising the usefulness of the extractions. In an effort to combat such noise, information extraction systems capture a vast array of features and statistics, ranging from the characteristics of the webpages used to generate extractions to the reliability of the particular patterns or techniques used to extract information. Using this host of features and a modest amount of training data, many information extraction systems employ heuristics or learned prediction functions to assign a confidence score to each candidate fact. These confidence scores capture the inherent uncertainty in the text from which the facts were extracted, and can ideally be used to improve the quality of the knowledge base.

While many information extraction systems use features derived from text to measure the quality of candidate facts, few take advantage of the many semantic dependencies between these facts. For example, many categories, such as “male” and “female” may be mutually exclusive, or restricted to a subset of entities, such as living organisms. Recently, the Semantic Web movement has developed standards and tools to express these dependencies through ontologies designed to capture the diverse information present on the Internet. The problem of building domain-specific ontologies for expert users with Semantic Web tools is challenging and well-researched, with high-quality ontologies for domains including bioinformatics, media such as music and books, and governmental data. More general ontologies have been developed for broad collections such as the online encyclopedia Wikipedia. These semantic constraints are valuable for improving the quality of knowledge bases, but incorporating these dependencies into existing information extraction systems is not straightforward.

The constraints imposed by an ontology are generally constraints between facts. For example, candidate facts assigning a particular entity to the categories “male”, “female”, and “living organism” are interrelated. Hence, leveraging the dependencies between facts in a knowledge base requires reasoning *jointly* about the extracted candidates. Due to the large scale at which information extraction sys-

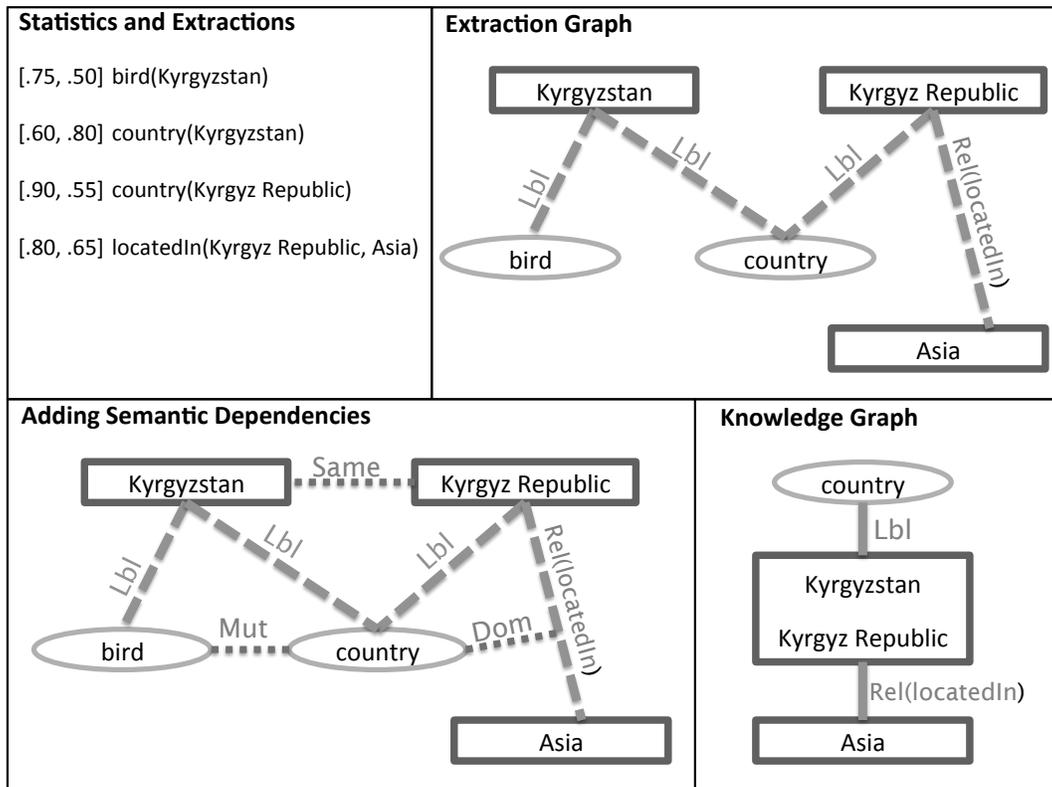


Figure 1: An illustration of (1) the conflicting candidate facts and statistics produced by an information extraction system, (2) their representation as an uncertain extraction graph, (3) semantic dependencies between facts introduced by an ontology, and (4) the final knowledge graph where errors have been removed by knowledge graph identification. Entities are shown in rectangles, labels are shown in circles, dashed lines represent uncertain information, dotted lines are used for ontological constraints and entity resolution, and solid lines represent the knowledge graph produced by knowledge graph identification.

tems operate, considering the dependencies between millions of candidates presents a scalability challenge. Logic-based approaches to reasoning about these candidates, such as automated theorem proving or constraint processing systems, are often impractical due to the uncertainty and errors in the candidate facts (Hitzler and van Harmelen, 2010). We describe a statistical relational learning (Getoor and Taskar, 2007) approach to the problem of constructing knowledge bases, applying recently developed techniques that incorporate statistical information and logical dependencies at scale.

Our approach uses a lightweight representation that we refer to as a *knowledge graph*. The knowledge graph contains the facts in the knowledge base, similar to the ABox in traditional knowledge representation approaches. In the knowledge graph, entities are represented as nodes, the attributes of each entity are node labels, and relationships between two or more entities are represented as edges. To build the knowledge graph, we use as input the entities, labels, and relationships produced by an information extraction system, which can be represented as an extraction graph. Noise, ambiguity, and errors limit the usefulness of the extraction graph. In this article, we summarize work on *knowledge graph identification* (Pujara et al., 2013), a process that infers

a knowledge graph from the extraction graph. In addition to the statistical properties of the extraction graph, knowledge graph identification incorporates semantics, in the form of an ontology and ontological constraints defined over the facts in the knowledge graph, to leverage dependencies between facts. These ontological constraints correspond to the TBox in knowledge representation terms. Figure 1 illustrates the noisy extraction graph that serves as an input to knowledge graph identification and the knowledge graph produced as output.

Statistical relational learning approaches can capture both the structure of the knowledge graph as well as the logical dependencies between the constituent facts. Unlike traditional reasoning systems, statistical relational learning approaches can treat ontological constraints as weighted rules, using them as “hints” to find the correct facts in a knowledge graph. For example, Jiang, Lowd, and Dou (2012) have demonstrated the effectiveness of Markov logic networks (MLNs) for jointly reasoning about the facts in a knowledge base.

Although MLNs provide a powerful approach to producing knowledge bases, their principal weakness is scalability. Here, instead, we use probabilistic soft logic

(PSL)(Broecheler, Mihalkova, and Getoor, 2010), a recently developed statistical relational learning approach. PSL shares many attractive features of MLNs: models can be specified using predicates and rules written in first-order logic syntax and translated into a probabilistic graphical model. In addition, PSL overcomes the scalability limitations of MLNs. Each logical predicate in an MLN has a Boolean truth value, and inference in these models is an intractable combinatorial optimization. As a result, many approximate methods for optimizing such models rely on sampling techniques for tractable inference. One of the key features of PSL is that predicates take continuous values in the  $[0, 1]$  range. By relaxing truth values to the continuous domain, PSL is able to solve inference tasks as an efficient convex optimization. In addition to improving scalability, continuous truth values provide a more suitable representation for statistical features, such as the confidence values of candidate facts. In this article, we show how implementing a PSL model for knowledge graph identification allows us to reason jointly over millions of facts efficiently, producing new state-of-the-art results. In addition, the improved scalability of our approach allows us to operate on datasets that are intractable for competing approaches to joint inference, such as MLNs.

### Knowledge Graph Identification: The Problem

The problem of jointly inferring the entities, labels, and relations in a graph from uncertain data through the processes of entity resolution, collective classification, and link prediction is referred to as graph identification (Namata, Kok, and Getoor, 2011). Similar to graph identification, knowledge graph identification completes these three tasks to infer the most probable knowledge graph from uncertain extractions. However, unlike graph identification, knowledge graph identification incorporates ontological constraints between facts during inference. We motivate the challenges presented by entity resolution, collective classification, and link prediction in knowledge graphs, then demonstrate how ontological information plays a vital role in each task. We draw examples from the Never-ending Language Learner (NELL), a large-scale information extraction system with a rich ontology, but the problems we identify are widespread in information extraction.

Entity extraction has a common problem: many textual references that initially look different may refer to the same real-world entity. For example, NELL’s knowledge base contains candidate facts involving the entities “kyrgyzstan”, “kyrgyzstan”, “kyrgystan”, “kyrgyz republic”, “kyrgyzstan”, and “kyrgistan” which are all variants or misspellings of the country Kyrgyzstan. In the extraction graph, each of these entities incorrectly correspond to different nodes. Our approach uses *entity resolution* to determine co-referent entities in the knowledge graph, producing a consistent set of labels and relations for each resolved node.

Another challenge in knowledge graph construction is inferring labels consistently. For example, NELL’s extractions assign Kyrgyzstan the labels “country” as well as “bird.” Ontological information suggests that an entity is very unlikely to be both a country and a bird simultaneously. More-

over, other extractions, for example that Bishkek is the capital of Kyrgyzstan, support the conclusion that Kyrgyzstan is a country. Using the labels of related entities in the knowledge graph can allow us to determine the correct label of an entity. Our approach uses *collective classification* to label nodes in manner which takes into account ontological information and neighboring labels.

A third problem commonly encountered in knowledge graphs is determining the relationships between entities. NELL also has many facts relating the location of Kyrgyzstan to other entities. These candidate relations include statements that Kyrgyzstan is located in Kazakhstan, Kyrgyzstan is located in Russia, Kyrgyzstan is located in the former Soviet Union, Kyrgyzstan is located in Asia, and that Kyrgyzstan is located in the US. Some of these possible relations are true, while others are clearly false and contradictory. Our approach uses *link prediction* to predict edges in a manner which takes into account ontological information and the rest of the inferred structure.

Each of these tasks are extremely challenging when posed as straightforward prediction tasks that do not use dependencies, and using only features from the information extraction system can cause these tasks to be underconstrained. Incorporating ontological constraints often resolves such difficulties. For example, understanding that co-referent entities such as “kyrgyzstan” and “kyrgyz republic” are the same entity and, as a result, should have the same labels and relations improves the quality of predicted labels and relations while also resolving ambiguity about these entities.

Multiple ontological constraints work in concert to improve the knowledge graph. NELL’s ontology includes the constraint that the labels “bird” and “country” are mutually exclusive. Ontological constraints also require the relation “locatedIn” relation to be a mapping from a domain of countries to a range of continents. Combining these constraints in knowledge graph identification produces dependencies between the location of entities and their potential labels. For example, the input to knowledge graph identification includes the erroneous extraction stating that “kyrgyzstan” has label “bird”. By combining the extractions that “kyrgyz republic” is located in Asia, and hence has label “country”, that “kyrgyz republic” and “kyrgyzstan” are co-referent, and that “bird” and “country” are mutually exclusive, we are able to remove the erroneous “bird” label. This complex set of dependencies requires jointly reasoning about millions of extractions simultaneously – a challenge we address in our model for knowledge graph identification.

### Knowledge Graph Identification: The Solution

Knowledge graph identification requires combining two disparate elements: the statistics output by an information extraction and ontological constraints derived from the semantics of the knowledge graph. In this section, we describe a model for knowledge graph identification using rules written in first-order logic syntax. We define predicates that capture candidate extractions, co-reference information and ontological knowledge and introduce rules that capture the relationships between these elements and the facts contained in the knowledge graph. However, since the inputs to this

model are uncertain values and statistics from an extraction system, the logical atoms in the rules take values between 0 and 1. We combine the rules and statistical inputs in a probabilistic graphical model to determine which facts to include in the knowledge graph.

In order to implement knowledge graph identification, our model uses probabilistic soft logic (PSL) (Broecheler, Mikhalkova, and Getoor, 2010), a recently introduced framework for specifying probabilistic graphical models over continuously-valued random variables. PSL provides many advantages: models are easily defined using declarative rules with first-order logic syntax, continuously-valued variables provide a convenient representation of uncertainty, weighted rules and weight learning capture the importance of model rules, and advanced features such as set-based aggregates and hard constraints are supported. Using PSL, we can transform the statistics and rules in our knowledge graph identification model into a probability distribution over knowledge graphs, and then infer the most likely knowledge graph. A significant obstacle to knowledge graph construction is scale - reasoning jointly over the millions of facts found in a knowledge graph is intractable in many models. However, in PSL this joint optimization is formulated as a convex objective that is highly scalable allowing us to handle millions of facts in minutes. After introducing each set of rules in our knowledge graph identification model, we will show how PSL transforms these rules into a probability distribution over knowledge graphs.

## Representation of Uncertain Extractions

Information extraction systems use a collection of techniques that operate on document features such as the structural elements (e.g. tables) lexical patterns (e.g. the phrase "president of"), or morphological features (e.g. capitalization). Each extractor produces a different set of outputs, and may assign each output a confidence value. The first step of building a knowledge graph is combining features and extractions from different extractors.

For example, an extractor based on structural elements might produce the label `bird(Kyrgyzstan)` and the relation `locatedIn(Kyrgyz Republic, Asia)` while a pattern-based classifier might produce the label `country(Kyrghyzstan)` as well as relations such as `hasCapital(Kyrgyz Republic, Bishkek)`. We use a different predicate for the candidates generated by each extractor. For a given extractor  $T$ , we introduce predicates  $\text{CANDREL}_T$  and  $\text{CANDLBL}_T$  to represent the candidates extracted by  $T$ . We relate these candidates to the unknown facts that we wish to infer, `LBL` and `REL` using the following rules:

$$\begin{aligned} \mathbf{w}_{\text{CR-}T} : \text{CANDREL}_T(E_1, E_2, R) &\Rightarrow \text{REL}(E_1, E_2, R) \\ \mathbf{w}_{\text{CL-}T} : \text{CANDLBL}_T(E, L) &\Rightarrow \text{LBL}(E, L) \end{aligned}$$

We define weights  $\mathbf{w}_{\text{CR-}T}$  and  $\mathbf{w}_{\text{CL-}T}$  for the relations and labels produced by extractor  $T$ , allowing us to compensate for the differing reliability of each technique. Using training data, we can use PSL to learn these weights. As a concrete example, a grounding of the structural extractor's candidate

`bird(Kyrgyzstan)` would produce the formula:

$$\begin{aligned} &\text{CANDLBL}_{\text{struct}}(\text{Kyrgyzstan}, \text{bird}) \\ &\Rightarrow \text{LBL}(\text{Kyrgyzstan}, \text{bird}) \end{aligned}$$

Since PSL uses *soft logic*, we can represent noisy extractions by translating confidences into real-valued truth assignments in the  $[0,1]$  range. For example, if the label extraction `bird(Kyrgyzstan)` has a confidence value of 0.6, we would assign the predicate  $\text{CANDLBL}_{\text{struct}}(\text{Kyrgyzstan}, \text{bird})$  a soft-truth value of 0.6. While these simple rules associate uncertain inputs with the facts in the knowledge graph, more complex rules allow us to incorporate knowledge about co-referent entities.

## Reasoning About Co-Referent Entities

Entity resolution identifies potentially co-referent entities and assigns a similarity score for each pair of entities. In the example above, many different variant forms for the country Kyrgyzstan appear: `Kyrgyzstan`, `Kyrghyzstan`, and `Kyrgyz Republic`. Knowledge graph identification employs entity resolution to pool information across these co-referent entities. We introduce the following rules to constrain the labels and relations of these co-referent entities:

$$\begin{aligned} \mathbf{w}_{\text{EL}} : \text{SAMEENT}(E_1, E_2) \wedge \text{LBL}(E_1, L) &\Rightarrow \text{LBL}(E_2, L) \\ \mathbf{w}_{\text{ER}} : \text{SAMEENT}(E_1, E_2) \wedge \text{REL}(E_1, E, R) &\Rightarrow \text{REL}(E_2, E, R) \\ \mathbf{w}_{\text{ER}} : \text{SAMEENT}(E_1, E_2) \wedge \text{REL}(E, E_1, R) &\Rightarrow \text{REL}(E, E_2, R) \end{aligned}$$

These rules define an equivalence class of entities, such that all entities related by the `SAMEENT` predicate must have the same labels and relations. The soft-truth value of the `SAMEENT`, derived from our similarity function, mediates the strength of these rules. When two entities are very similar, they will have a high truth value for `SAMEENT`, so any label assigned to the first entity will also be assigned to the second entity. On the other hand, if the similarity score for two entities is low, the truth values of their respective labels and relations will not be strongly constrained.

## Incorporating Ontological Information

Although entity resolution allows us to relate extractions that refer to the same entity, knowledge graphs can employ ontological information to specify rich relationships between many facts. Our ontological constraints are based on the logical formulation proposed in (Jiang, Lowd, and Dou, 2012). Each type of ontological relation is represented as a predicate, and these predicates represent ontological knowledge of the relationships between labels and relations. For example, the domain and range constraints  $\text{DOM}(\text{locatedIn}, \text{country})$  and  $\text{RNG}(\text{locatedIn}, \text{continent})$  specify that the relation `locatedIn` is a mapping from entities with label `country` to entities with label `continent`. The mutual exclusion constraint  $\text{MUT}(\text{country}, \text{bird})$  specifies that the labels `country` and `bird`; are mutually exclusive, so that an entity cannot have both the labels `country` and `bird`. We similarly use constraints for subsumption of labels (`SUB`) and inversely-related functions (`INV`). To use this ontological knowledge, we introduce rules

relating each ontological relation to the predicates representing our knowledge graph. We specify seven types of ontological constraints in our experiments:

$$\begin{aligned}
w_O : \text{DOM}(R, L) &\wedge \text{REL}(E_1, E_2, R) \Rightarrow \text{LBL}(E_1, L) \\
w_O : \text{RNG}(R, L) &\wedge \text{REL}(E_1, E_2, R) \Rightarrow \text{LBL}(E_2, L) \\
w_O : \text{INV}(R, S) &\wedge \text{REL}(E_1, E_2, R) \Rightarrow \text{REL}(E_2, E_1, S) \\
w_O : \text{SUB}(L, P) &\wedge \text{LBL}(E, L) \Rightarrow \text{LBL}(E, P) \\
w_O : \text{RSUB}(R, S) &\wedge \text{REL}(E_1, E_2, R) \Rightarrow \text{REL}(E_1, E_2, S) \\
w_O : \text{MUT}(L_1, L_2) &\wedge \text{LBL}(E, L_1) \Rightarrow \neg \text{LBL}(E, L_2) \\
w_O : \text{RMUT}(R, S) &\wedge \text{REL}(E_1, E_2, R) \Rightarrow \neg \text{REL}(E_1, E_2, S)
\end{aligned}$$

## Putting It All Together

Constructing a knowledge graph is challenging because of the many interactions between uncertain extractions, co-references, ontological information, and facts in the knowledge graph. To capture the complex set of dependencies in the knowledge graph, we formulate the problem as a probabilistic graphical model. Figure 2 illustrates a small portion of the graphical model associated with the example in this section. Each possible fact in the in the knowledge graph is a variable in the model. Dependencies between variables derived are from rules. These dependencies are shown as factors between variables, shown using  $\phi$  labels. Each  $\phi$  is a function of the variable values that measures a *distance to satisfaction* of the variables’ truth values relative to the rules, where a high distance to satisfaction indicates a violated rule or constraint. For example, if the variables  $\text{LBL}(\text{Kyrgyzstan}, \text{bird})$  and  $\text{LBL}(\text{Kyrgyzstan}, \text{country})$  both had high truth values, the factor  $\phi_5$  representing a mutual exclusion constraint between these variables would have a high distance to satisfaction. Similarly, the factor  $\phi_3$  will have a low distance to satisfaction for co-referent entities  $\text{Kyrgyzstan}$  and  $\text{Kyrgyz Republic}$  when both have the same label,  $\text{country}$ .

To determine the value of each variable in the model, we use PSL to define a joint probability distribution over the different possible knowledge graphs. The universally-quantified rules described above form a PSL model and provide the basis for defining this probability distribution. In a PSL program,  $\Pi$ , this model is *grounded* by substituting values from the extractions and ontology into the rule templates. Unlike Boolean logic where each grounding would have a binary truth value, our choice of soft-logic requires a different definition of truth value. We relax truth values in the knowledge graph  $G$  to the  $[0, 1]$  interval and use a logically-consistent interpretation to determine the truth values of ground logical formulas. With this definition, we can assign a truth value  $T_r(G)$  to each grounding  $r \in R$  and define a distance to satisfaction,  $\phi_r(G) = (1 - T_r(G))^2$  for each grounding. The probability distribution over knowledge graphs,  $P_\Pi(G)$  can now be defined in terms of the weighted combination of the distances to satisfaction of ground rules in the PSL program:

$$P_\Pi(G) = \frac{1}{Z} \exp \left[ - \sum_{r \in R} w_r \phi_r(G) \right]$$

Given this distribution, the task of most probable explanation (MPE) inference corresponds to finding the soft-truth values of every fact in the knowledge graph  $G$  that maximize the value of this probability distribution. The soft-truth values of variables can be interpreted as confidences. In our work, we choose a soft-truth threshold and determine the true entities, labels and relations by using those atoms whose truth value exceeds the threshold. By using a small validation set to choose this threshold, we can balance precision and recall of the resulting knowledge graph as required by a particular application.

The myriad dependencies in the knowledge graph identification model are a formidable scalability challenge. In PSL, MPE inference can be formulated as convex optimization. Solving this convex optimization using the Alternating Direction Method of Multipliers (ADMM), Bach et al. (2012) have shown performance that scales linearly with the number of ground rules in the PSL program. In practice, this allows our model implementing knowledge graph identification to jointly infer the values of millions of variables in the knowledge graph in just hours – a result we detail in the next section.

## Evaluation

We highlight the effectiveness of knowledge graph identification with results for building a knowledge graph with data from NELL, a large-scale information extraction system operating on text from the WWW. Our experiments contrast two very different evaluation settings. The first, used in prior work, restricts knowledge graph inference to a small subset of variables and excludes some contradictory values. Our results in this simpler setting improve on the state-of-the-art results while completing the inference task in just seconds. In the second evaluation setting, we apply knowledge graph identification to infer the complete knowledge graph, operating over the space of all possible knowledge graphs and handling millions of variables and tens of millions of dependencies. Despite the magnitude of this inference task, our implementation of knowledge graph identification requires just over two hours to complete and improves on the performance of the existing NELL system. Data and code for these experiments are available on GitHub<sup>1</sup>.

**NELL Dataset** The Never-ending Language Learner is a system that seeks to iteratively create a knowledge base by constantly improving its ability to process text and extract information. In each iteration, NELL uses facts learned from the previous iteration and a corpus of web pages to generate a new set of candidate facts. Our experimental results are on data from the 165th iteration of NELL, using the candidate facts, previously promoted facts and ontological relationships that NELL used during that iteration. We summarize the important statistics of this dataset in Table 1. NELL uses diverse extraction techniques, and we use distinct predicates for the most prominent sources, while averaging values across extractors that do not contribute a significant number of facts. In addition to these candidate facts, NELL uses

<sup>1</sup><https://github.com/linqs/KnowledgeGraphIdentification>

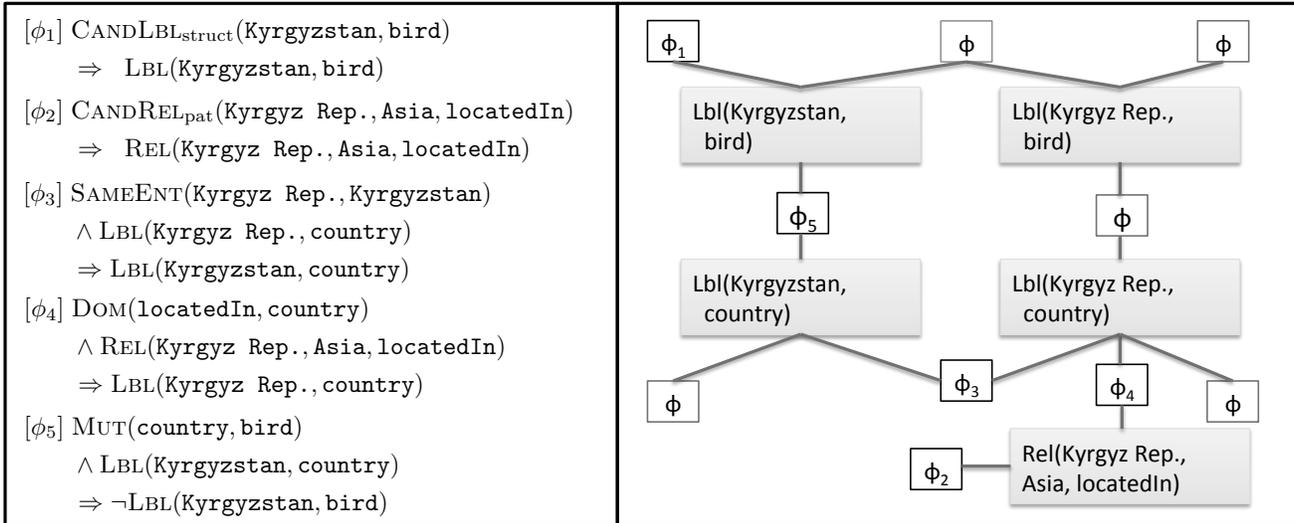


Figure 2: A subset of the probabilistic graphical model defined by the rules in PSL in our example. Each potential fact in the knowledge graph is a variable, and factors ( $\phi$ ) represent a *distance to satisfaction* capturing dependencies between variables.

a heuristic formula to selectively “promote” candidates in each iteration of the system into a knowledge base, however these promotions are often noisy so the system assigns each promotion a confidence value. We represent these promoted candidates from previous iterations as an additional source with corresponding candidate predicates.

**Entity Coreference** Knowledge graph identification also incorporates entity co-references, a feature missing from the NELL data. We derive entity co-reference by using the YAGO database (Suchanek, Kasneci, and Weikum, 2007) as part of our entity resolution approach. The YAGO database contains entities which correspond to Wikipedia articles, variant spellings and abbreviations of these entities, and associated WordNet categories. We match entity names in NELL with YAGO entities. We perform selective stemming on the NELL entities, employ blocking on candidate labels, and use a case-insensitive string match to find corresponding YAGO entities. Once we find a matching set of YAGO entities, we can generate a set of Wikipedia URLs that map to the corresponding NELL entities. Our model uses a SAMEENT predicate to capture the similarity of two entities. We then define a similarity function on the article URLs and use the computed similarity as the soft-truth value of the SAMEENT predicate. For our similarity score we use the Jaccard index, the ratio of the size of the set intersection and the size of the set union.

**Evaluation Scenarios** In our experiments using NELL, we consider two scenarios. The first is similar to experimental setup in (Jiang, Lowd, and Dou, 2012) where rule weights are learned using training data and predictions are made on a limited 2-hop neighborhood of the test set. The neighborhood used in this previous work attempts to improve scalability by generating a grounding of the rules using atoms in the test set and

only including additional atoms that are not trivially satisfied in this grounding. In practice, this produces a neighborhood that is distorted by omitting atoms that may contradict those in the test set. For example, if ontological relationships such as SUB(country, location) and MUT(country, city) are present, the test set atom LBL(Kyrgyzstan, country) would not introduce LBL(Kyrgyzstan, city) or LBL(Kyrgyzstan, location) into the neighborhood, even if contradictory data were present in the input candidates. By removing the ability to reason about contradictory information, we believe this evaluation setting diminishes the true difficulty of the problem. We validate our approach on this setting, but also present results from a more realistic setting. In the second scenario we perform inference independently of the test set, lazily generating target variables for atoms supported by the input data, using a soft-truth value threshold of .01. This second setting allows us to infer a complete knowledge graph with truth values for all possible variables, including those that may contradict the atoms in the test set.

## Knowledge Graph Identification Results for NELL

**Comparison to Previous Work** We compare our method against previously reported results on a manually-labeled evaluation set of 4,500 facts (Jiang, Lowd, and Dou, 2012). A summary of these results is shown in Table 2, where the best-performing method is shown in boldface. The first method we compare to is a baseline where candidates are given a soft-truth value equal to the extractor confidence (averaged across extractors when appropriate). Results are reported at a soft-truth threshold of .45 which maximizes F1.

We also compare the default strategy used by the NELL project to choose candidate facts to include in the knowledge base. Their method uses the ontology to check the consis-

Table 1: Summary of dataset statistics for NELL, including the number of candidate facts in input data, the distinct relations and labels present, and the number of ontological relationships defined between these relations and labels

Cand. Label	1.2M
Cand. Rel	100K
Promotions	440K
Unique Labels	235
Unique Rels	221
DOM	418
RNG	418
INV	418
MUT	17.4K
RMUT	48.5K
SUB	288
RSUB	461

tency of each proposed candidate with previously promoted facts already in the knowledge base. Candidates that do not contradict previous knowledge are ranked using a heuristic rule based on the confidence scores of the extractors, and the top candidates are chosen for promotion subject to score and rank thresholds. Note that the NELL method includes judgments for all input facts, not just those in the test set.

The third method we compare against is the best-performing MLN model from Jiang, Lowd, and Dou (2012), that expresses ontological constraints, and candidate and promoted facts through logical rules similar to those in our model. The MLN uses additional predicates that have confidence values taken from a logistic regression classifier trained using manually labeled data. The MLN uses hard ontological constraints, learns rule weights considering rules independently and using logistic regression, scales weights by the extractor confidences, and uses MCMC with a restricted set of atoms to perform approximate inference, reporting output at a .5 marginal probability cutoff, which maximizes the F1 score. The MLN method only generates predictions for a 2-hop neighborhood generated by conditioning on the values of the query set, as described earlier.

Our method, PSL-KGI, implements the KGI model in PSL using weighted rules for ontological constraints, entity resolution, and candidate and promoted facts as well as incorporating a prior. We also incorporate the predicates generated for the MLN method for a more equal comparison. We learn weights for all rules, including the prior, using a voted perceptron learning method. The weight learning method generates a set of target values by running inference and conditioning on the training data, and then chooses weights that maximize the agreement with these targets in absence of training data. Since we represent extractor confidence values as soft-truth values, we do not scale the weights of these rules. Using the learned weights, we perform inference on the same neighborhood defined by the query set that is used by the MLN method. We report these results, using a soft-truth threshold of .55 to maximize F1, as PSL-KGI.

Table 2: Comparing against previous work on the NELL dataset, knowledge graph identification using PSL demonstrates a substantive improvement. The best-performing method is shown in boldface.

Method	AUC	F1
Baseline	0.873	0.828
NELL	0.765	0.673
MLN	0.899	0.836
PSL-KGI	<b>0.904</b>	<b>0.853</b>

Table 3: Comparing variants of PSL graph identification show the importance of ontological information, but the best performance is achieved when all of the components of knowledge graph identification are combined.

Method	AUC	F1
PSL-NoSrcs	0.900	0.852
PSL-NoER	0.899	<b>0.853</b>
PSL-NoOnto	0.887	0.826
PSL-KGI	<b>0.904</b>	<b>0.853</b>

In Table 2 we report area under the precision-recall curve (AUC) and F1 measure, the harmonic mean of the precision and recall. Our implementation of knowledge graph identification improves on the baseline, the NELL promotion strategy, and the previous state-of-the-art results using MLNs, with a modest improvement in AUC and a substantial improvement in the F1 measure.

### Analyzing Variations of Knowledge Graph Identification

To better understand the contributions of various components of our knowledge graph identification model, we explore variants that omit one aspect of the model: capturing different extraction sources, using entity co-reference information, and the ontological constraints between facts. We compare the results for each of these treatments in Table 3. PSL-NoSrcs removes predicates  $CANDL_{BLT}$  and  $CANDREL_T$  for different candidate sources, replacing them with a single predicate using the average confidence value across sources. PSL-NoER removes rules used to reason about co-referent entities, easing the constraint that co-referent entities share the same labels and relations. PSL-NoOnto removes rules for using ontological relationships to constrain the knowledge graph, removing many of the dependencies necessary for consistency. Removing source information and entity resolution each reduce the performance of our model slightly, but the large drop in AUC and F1 measure when ontological information is removed suggests that the ontology is the principal contributor to the success of knowledge graph identification.

One drawback of our comparisons to previous work is the restriction of the model to a small set of inference targets. The construction of this set obscures some of the challenges presented in real-world data, such as conflicting evidence. To assess the performance of our method in a setting where inference targets do not restrict potentially contradictory in-

Table 4: Producing a complete knowledge graph reduces performance on the test set, suggesting that the true complexity of the problem is masked when generating a limited set of inferences.

Method	AUC	F1
NELL	0.765	0.673
<i>PSL-KGI</i>	0.904	0.853
PSL-KGI-Complete	<b>0.892</b>	<b>0.848</b>

ferences, we also ran knowledge graph identification using the same learned weights but with no predefined set of targets, allowing lazy inference to produce a complete knowledge graph. The resulting inference produces a total of 4.9M facts, which subsumes the test set. We report results of this process in table 4 as PSL-KGI-Complete, using the same evaluation set as previous experiments. Allowing the model to optimize on the full knowledge graph instead of just the test set reduced the performance on the test set, suggesting that the noise introduced by conflicting evidence does have an impact on results. Despite the difficulties of inference in this more complex setting, running inference on the full knowledge graph improves AUC and F1 relative to the heuristics NELL uses to produce its knowledge base.

**Scalability** One advantage of using PSL for knowledge graph identification is the ability to frame complex joint reasoning as a convex optimization. Knowledge graph identification implemented in PSL can handle problems from real-world datasets like NELL, which include millions of candidate facts. Inference when an explicit query set of 70K facts is given (PSL-KGI) requires a mere 10 seconds. The MLN method we compare against takes a few minutes to an hour to run for the same setting. When inferring a complete knowledge graph without known query targets, as in the last NELL experiment, inference with MLNs is infeasible. In contrast, knowledge graph identification on the NELL dataset can produce the complete knowledge graph containing 4.9M facts in only 130 minutes. The ability to produce complete knowledge graphs in these realistic settings is an important feature of our implementation of knowledge graph identification.

## Conclusion

Successfully combining statistical features and semantic relationships is a common theme in artificial intelligence research. In this article, we describe a statistical relational learning approach for combining these two disparate sources of knowledge. Specifically, we show how the noisy candidate facts and statistical features produced by an information extraction system can be combined with semantic constraints derived from an ontology to produce a knowledge base. Using the knowledge graph representation for the knowledge base, we describe the problem of *knowledge graph identification*: jointly inferring the most likely knowledge graph. Our model for knowledge graph identification defines a probability distribution over possible knowledge graphs using a series of logical formulas. Scalability is a

key concern for inference in joint models, however using probabilistic soft logic allows us to solve the MPE inference problem through an efficient convex optimization. In our results on data from the NELL project, we demonstrate that knowledge graph identification is capable of producing superior knowledge graphs while scaling to problems that are intractable for competing models. In future work, we plan to extend knowledge graph identification to address constantly growing and changing web data.

**Acknowledgments** We would like to thank Shangpu Jiang and Daniel Lowd for sharing their data and offering enthusiastic assistance. This work was partially supported by NSF CAREER grant 0746930, NSF grants IIS1218488 and CCF0937094, and Google Research grants. Any opinions, findings, and conclusions or recommendations expressed in this material are those of the author(s) and do not necessarily reflect the views of the National Science Foundation.

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